

Communication server PLCComS

User manual

14. edition - January 2016

History of changes

Date	Version	Description of the changes
March 2010	1	First version.
April 2010	2	Processing variables of types <i>date</i> , <i>dt</i> , <i>time</i> a <i>tod</i> . Extending the example of processing of file attributes.
August 2010	3	Links to shared module were added. Extension and modification of the configuration file. Color highlighting examples in “C” language. Chapter with examples of application server and licenses was added.
June 2011	4	Extending the configuration file..
August 2011	5	Extended description of chapter 3.2 User public file . Table 5.1 List of messages corrected.
September 2011	6	Chapter 7 Licence corrected and table 8 Supported Operating Systems extended.
October 2011	7	Chapters 2.1 Example of the configuration file , 4 Client protocol and table 4.1 List of commands edited.
March 2013	8	Chapter 4.2.2 Command SET: edited.
August 2013	9	Chapter 2.1 Example of the configuration file edited and table 8 Supported Operating Systems extended.
May 2014	10	Chapter 2.1 Example of the configuration file edited. Table 4.1 List of commands and 5.1 List of messages extended. Chapter 4.2.6 Command GETMEM: added and chapter 4.2.9 Command GETINFO: updated.
May 2014	11	Chapter 2.1 Example of the configuration file edited.
Sept 2014	12	Chapter 2.1 Example of the configuration file and 4.2.9 Command GETINFO: edited. Table 4.1 List of commands and 5.1 List of messages extended.
November 2014	13	Chapter 1 System description , 2.1 Example of the configuration file , 3 Configuration public file , 3.2 User public file , 4 Client protocol , 4.2.2 Command SET: , 4.2.4 Command EN: , 4.2.5 Command DI: , 4.2.7 Command GETFILE: edited. Table 4.1 List of commands and 5.1 List of messages edited.
January 2016	14	Chapter 2.1 Example of the configuration file , 3 Configuration public file and 4.2.9 Command GETINFO: edited. Table 4.1 List of commands and 5.1 List of messages extended.

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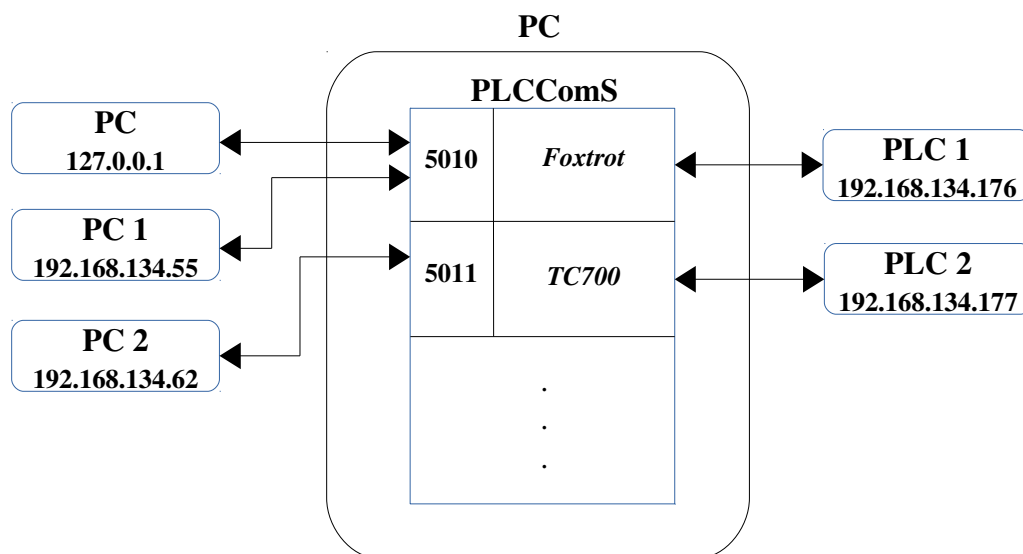
1 System description

Communication server provides TCP/IP connection between client device and PLC.

Server communication with clients is solved using a simple text-oriented protocol REQUEST/ANSWER. Therefore, the client queries the server by commands (*Chap. 4.1*) for the values of variables whose names are symbolic and are described in *public* file (*Chap. 3*). However, it is possible to use direct addressing (*Chap. 4.2.2*). Server sends to client only error messages and variables whose values have changed.

Server communicates with the PLC using the optimized protocol EPSNET or with shared module in case of SoftPLC. The values of variables are polled by absolute addressing and periodically in time increments of 100ms.

Configuration is set in *ini* file.



Server can be run with the following parameters:

PLCComS [-dh] [-c <configuration_file>] [-l <log_file>]

<i>-d, --daemon</i>	<i>Server runs in the background.</i>
<i>-c, --config</i>	<i>Configuration file.</i>
<i>-l, --log</i>	<i>Log file.</i>
<i>-h, --help</i>	<i>Displays help.</i>

In case of run with parameter *-d* the server runs in the background and all reports are forwarded to a log file. Unless its name is specified, it is set to "PLCComS.log". This option is only available in a version for the Linux operating system.

In case the parameter was not specified *-c*, its name is set for "PLCComS.ini".

Unless the parameter *-l*, is not specified all the reports are sent to the terminal server from which it was run.

2 Configuration *ini* file

It consists of sections where the section marked as “[*]” is mandatory and contains global settings. Behind this section the others follow describing the setting for the particular PLC. There must be at least one such section. The name of such section can be any except “*”. The name is used in the log file entries for convenience.

2.1 Example of the configuration file

```
[*]

COMM_LOOP_DELAY = 100    # The delay in the main loop ([1 - 1000]ms)
NET_CONNECT_MAX  = 128    # Maximum number of client connections (Maximum is
                           1024)
MEM_BLKSIZE      = 4096   # Block size in bytes for transfer PLC memory
                           (Maximum is 65536)
FFILE_BLKSIZE    = 16384  # The block size in KB for file transfer
                           # (Maximum is 65536)
FFILE_TIMEOUT    = 300    # The time limit of the file (Maximum is 3600)
FFILE_MAXRECS    = 256    # Number of files stored in the memory
                           (Maximum is 1024)
END_LINE_CRLF    = Yes    # End character of the line (Yes = DOS [\r\n],
                           No = UNIX[\n])
PF_VAR_DISABLED  = Yes    # The default state of variables
DIFF_VAR_ENABLED = Yes    # Disables or enables listings DIFF: messages
SYNC_VAR_ENABLED = Yes    # Enable or disable synchronization variables with
                           PLC while downloading files.
LIM_OF_DECIMALS  = No     # Restricts precision floating point numbers to
                           generate DIFF: messages (Yes = restrict)
NUM_OF_DECIMALS  = 10     # The number of decimal digits that will be displayed
                           or restricted ([0 - 6] REAL, [0 - 15] LREAL)
SCIENT_NOTATION  = No     # Scientific notation for REAL a LREAL (Yes =
                           scientific [-]d.ddd e[+/-]ddd, No = normal
                           [-]ddd.ddd)

#[Symbolic name of PLC]

#IPADDR          = IP address PLC
#EPSADDR         = EPSNET source address (1 - 126). If not set, will be gene-
rated automatically.
#EPSTOUT         = EPSNET timeout ([1 - 15000]ms). If not set, will be used
default value 1000ms.
#EPSTOUT_STEP    = EPSNET timeout step ([0 - 5000]ms). If not set, will be used
default value 500ms.
#EPSPORT        = EPSNET communication port. Useful for service TECOROUTE. If
not set, will be used default value 61682.
#SERVER_PORT     = The port number on which the client will communicate with the
PLC
#SERIAL_DEVICE   = Name of serial line
#SERIAL_SPEED    = Communication speed for serial line
#SERIAL_RTS      = Number of GPIO pin for flow control. If not set, hardware
flow control will be used.
#SHM_NAME        = Name of the shared module (library *.dll or *.so)
#SHM_SOCKET      = Socket number for communicating with a shared module
#SHM_PORT        = Port number for communicating with a shared module
#PUBFILE_CRC     = Turn On/Off the CRC check of public file. [Yes/No]
#PUBFILE_WRITE   = Turn On/Off the write public file to local disk. [Yes/No]
#PUBFILE         = Name of public file.
#PUBFILE_FIXED   = Name of fixed public file.
```

[Foxtrot]

IPADDR = 192.168.134.176
SERVER_PORT = 5010
PUBFILE_CRC = Yes
PUBFILE_WRITE = No
PUBFILE_FIXED = FIXED_Foxtrot.pub
PUBFILE = //www/webmaker.pub

[TC700]

IPADDR = 192.168.134.177
SERVER_PORT = 5011
PUBFILE_CRC = Yes
PUBFILE_WRITE = No
PUBFILE_FIXED = FIXED_TC700.pub
PUBFILE = //www/webmaker.PUB

[TC700 RS232]

SERIAL_DEVICE = /dev/ttyS0
SERIAL_SPEED = 115200
SERVER_PORT = 5012
PUBFILE_CRC = Yes
PUBFILE_WRITE = No
PUBFILE_FIXED = FIXED_TC700.pub
PUBFILE = //www/webmaker.PUB

[SoftPLC]

SERVER_PORT = 5013
SHM_NAME = ShmSrv.dll
SHM_SOCKET = 0
SHM_PORT = 5
PUBFILE_CRC = Yes
PUBFILE_WRITE = No
PUBFILE_FIXED = FIXED_SoftPLC.pub
PUBFILE = //www/webmaker.pub

3 Configuration *public* file

Describes the correlation between the variable name and physical address register in the PLC. Two types of file are used, fixed and user. Fixed file is stored in the directory from which the server is running. User file can be stored either locally or in the PLC. In the case of local storage file is the root directory depends on the settings of the variable PUBFILE_WRITE. They drove this variable is set to "No" or in *ini* file is missing, then the root directory in same place from which the server is running. They drove this variable is set to "Yes", then the root subdirectory whose name is negotiable with the name of the section in the *ini* file and is located in the directory from which the server is running. By specifying a relative path, it is possible to access local files stored outside this root directory. When you open a file the file that is stored locally has the priority. If not found, it tries to open a file in the PLC. If the file name starts with "/" the root directory is mentioned.

3.1 Fixed *public* file

Is the file needed for the actual operation of the server. It contains a variables with which it is possible to work in the same way as with variables from the user *public* file. With the exception of command "DI:", which ignores that variables.

3.1.1 List of variables

Name	Data type	Meaning
__PLC_RUN	BOOL	Status of PLC. (1 = RUN, 0 = HALT)
__PF_CRC	DWORD	CRC value of user <i>public</i> file. when it is changed, the server automatically retrieves if by new <i>public</i> file.

3.2 User *public* file

Is the file generated by the *Mosaic* user program development package. The variables in this file are connected by the server to variables from *fixed* file. In case of a collision of names the variables in this file are ignored.

The file is provided with a CRC value that is equal to the value of the variable __PF_CRC. Changing the value of this variable represents the change in the PLC project (i.e. user program). Thus the server monitors this change and if it occurs, will load a new file and report this to the client by message "WARNING:250 Changed public file: 'Test.pub'". If the contents of the new file does not differ from the current, the new file is not downloaded and the client is notified that the message „WARNING:251 Public file not changed: 'Test.pub'“.

4 Client protocol

A text-based protocol, where each statement is terminated by character “:” and each end of line either by “\r\n” (DOS) or “\n” (UNIX). Type a line terminator is selectable in configuration file or by the command “*SETCONF:*”. Settings using the command “*SETCONF:*” affects only the client that set it out. The command names are not case sensitive, and therefore perhaps any combination is allowed. To test the connection, or diagnostics *Telnet* program can be used, where it is possible to close the connection using the escape sequence “ctrl+d”.

4.1 List of commands

Command	Description
<i>LIST:\n</i>	List all variables from <i>public</i> files.
<i>SET:<variable_name, value>\n</i>	Sets a variable in the PLC to the specified value.
<i>GET:<variable_name>\n</i>	Gets the value of a variable of the PLC.
<i>EN:[variable_name] [delta]\n</i>	Enable the variable(s) from <i>public</i> file and set it to change the <i>delta</i> .
<i>DI:[variable_name] [delta]\n</i>	Enable the variable(s) from <i>public</i> file and set it to change the <i>delta</i> .
<i>GETMEM:<variable_name mem_size></i>	Get memory block from PLC.
<i>GETFILE:<file_name>\n</i>	Gets the file from PLC
<i>GETFILEINFO:<file_name>\n</i>	Gets the information about the file stored in PLC.
<i>GETINFO:[name]\n</i> <i>Name</i>	Lists information about the communication server.
<i>version</i>	Version of the communication server.
<i>epsnet_version</i>	Version of Epsnet library.
<i>version_ini</i>	Version of <i>ini</i> parsing library.
<i>version_plc</i>	PLC version.
<i>epsaddr</i>	EPSNET source address.
<i>epsport</i>	EPSNET communication port.
<i>ipaddr_plc</i>	IP address of PLC.
<i>serial_device</i>	Settings of serial line.
<i>pubfile</i>	The names of actual <i>public</i> files.
<i>network</i>	List of connected clients.

<p><i>SETCONF:<variable_name, value>\n</i></p> <p><i>variable name:</i></p> <p><i>ipaddr</i></p> <p><i>epsaddr</i></p> <p><i>epsport</i></p> <p><i>serial_device</i></p> <p><i>serial_speed</i></p> <p><i>pubfile</i></p> <p><i>crlf</i></p> <p><i>diff</i></p> <p><i>HELP:\n</i></p>	<p>Change the value of the variable specified in the configuration <i>ini</i> file.</p> <p>IP address of PLC.</p> <p>EPSNET source address (1 - 126).</p> <p>EPSNET communication port.</p> <p>Name of serial line.</p> <p>Communication speed for serial line.</p> <p>Public file.</p> <p>End of line character (yes = DOS, no = UNIX).</p> <p>Suppress message list “<i>DIFF:</i>” (yes / no).</p> <p>List the help</p>
---	---

When entering the name of variables you can use wild cards. The character “*” in the name replaces any number of characters. Number of characters “*” is not limited.

The server response always begins with the name of the command that caused it. With exception of “*SET:*” command, where the answer starts with “*DIFF:*”. Thus in case that this response was not disabled (*Chap. 2, 4*). In case of command, where the answers can give multiple results, the list of server responses is terminated by the command name itself.

Example of list of variables whose name starts with “test_” string:

Query:

*GET:test_ *\n*

Answer:

GET:test_1,123\n

GET:test_2,1.234500\n

GET:\n

Example query to specific variable:

Query:

GET:test_1\n

Answer:

GET:test_1,123\n

4.2 Client protocol - examples

4.2.1 Command LIST:

Query:

LIST:\n

Answer:

LIST:test_1\n

LIST:test_2\n

LIST:test_string\n

LIST:test_btn\n*

LIST:\n

The character “*” at the end of the variable name means the prohibited variable. Handling with such variable by commands e.g. “GET:” or “SET:” results the error (*Chap. 5*).

4.2.2 Command SET:

Query:

SET:test_1,123\n

Answer:

DIFF:test_1,123\n

Query:

SET:test_string,"Hello!"\n

Answer:

DIFF:test_string,"Hello!"\n

Answer beginning with string “DIFF:” is server response for the change of some variable in PLC. In combination with the command “SET:” it can be used to check if the variable was really changed. The answer “DIFF:” is not generated in the event that the variable has not changed or the change was not greater than the value of the deviation *delta*. Thus, if the variable has been set (*Chap. 4.2.4, 4.2.5*).

Values of variables of type *string* are placed in quotation marks. Values of variables of type *bool*, is possible to set by the expression *true* (1) or *false* (0). The answer is always value 1 or 0.

If the variable name instead of using a direct address, the format is as follows: %<name of register><address of register>

Example: %R100, %S6, ...

4.2.3 Command GET:

Query:

GET:test_1\n

Answer:

GET:test_1,123\n

Query:

GET:test_string\n

Answer:

GET:test_string,"Hello!"\n

In case of query for value of type *date* or *dt* the value is sent as 64-bit unsigned integer, even if the standard define the variable as type real. It is because of possible rounding during transmission. The fractional part contains the amount of milliseconds.

Examples in “C” language:

```
time_t t;
struct tm *tm;
unsigned int ms;
unsigned long long int ldate;
double date;

...

sscanf (msg, "%llu", &ldate);

date = *(double *) &ldate;

ms = (unsigned int) ((date - (unsigned long long int) date) * 1000);

t = (time_t) date;
tm = gmtime (&t);

if (tm == NULL)
    return 1;

printf ("Date: %02d.%02d.%d", tm->tm_mday, tm->tm_mon + 1, tm->tm_year +
1900);
printf ("Time: %02d:%02d:%02d.%03d", tm->tm_hour, tm->tm_min, tm->tm_sec, ms);

...
```

If the variable is of type *time* or *tod* the server sends the value as 32-bit unsigned integer as is defined in the standard.

Example in “C” language:

```
struct tm tm;  
unsigned long time;  
  
...  
  
sscanf (msg, "%lu", &time);  
  
memset (&tm, 0, sizeof (struct tm));  
  
tm.tm_hour = time / 3600000;  
time -= (tm.tm_hour * 3600000);  
tm.tm_min = time / 60000;  
time -= (tm.tm_min * 60000);  
tm.tm_sec = time / 1000;  
tm.tm_isdst = time - (tm.tm_sec * 1000);  
  
printf ("Time: %02d:%02d:%02d", tm.tm_hour, tm.tm_min, tm.tm_sec);  
  
...
```

4.2.4 Command EN:

Query:

EN:\n

EN:temperature 0.5\n

4.2.5 Command DI:

Query:

DI:\n

DI:lighting 10\n

Commands “EN” and “DI” enable or disable variables in communication table of the server. If the variables are disabled, server does not ask the PLC for them. Thus the volume of data to be transferred is decreased. Disabling does not affect the variables in the fixed *public* file. For variable name can be specified deviation *delta*. This deviation is used to limit the number of “DIFF:” messages.

4.2.6 Command GETMEM:

Query:

GETMEM:test_string 6\n

Answer:

GETMEM:test_string[6]=Hello!\n

GETMEM:test_string[0]=\n

The contents of the memory is transferred in blocks of size given by variable MEM_BLKSIZE, which is set in configuration *ini* file. The actual length of the block is indicated in brackets at the end of the variable name.

4.2.7 Command GETFILE:

Query:

```
GETFILE://www/TEST.TXT\n
```

Answer:

```
GETFILE://www/TEST.TXT[20]=This is test string.\n
```

```
GETFILE://www/TEST.TXT[0]=\n
```

The contents of the file is transferred in blocks of size given by variable FFILE_BLKSIZE, which is set in configuration *ini* file. The actual length of the block is indicated in brackets at the end of the file name. If the file name ends with “/”, it is a directory and transmits its contents.

4.2.8 Command GETFILEINFO:

Query:

```
GETFILEINFO://www/TEST.TXT\n
```

Answer:

```
GETFILEINFO://www/TEST.TXT[35]=21 32 59391128503405 5939112850  
3405\n
```

The actual length of the block is indicated in brackets at the end of the file name.

Structure of the message:

size attributes time_creation time_change

size - size of file in bytes.

attributes - 32 bit number interpreted per bits.

time_creation - 64 bit number which can be interpreted by the structure *ttida*.

time_change - 64 bit number, which can be interpreted by the structure *ttida*.

4.2.8.1 List of *attributes*

Hexadecimal value	Meaning
0x00000001	Only for reading
0x00000002	Hidden file
0x00000004	The system file
0x00000010	The file is a directory
0x00000020	The archive file

structure *ttida* - Size 8 bytes (year, month, day, hour, minute, second, nothing, nothing).

Example in “C” language:

```
#define FILE_ATTRIBUTE_READONLY          0x00000001
#define FILE_ATTRIBUTE_HIDDEN           0x00000002
#define FILE_ATTRIBUTE_SYSTEM           0x00000004
#define FILE_ATTRIBUTE_DIRECTORY        0x00000010
#define FILE_ATTRIBUTE_ARCHIVE          0x00000020

struct ttida {char year; char mon; char day; char hour; char min; char sec;
              char none1; char none2;} tida_c, tida_m;

...

long size, attr;

sscanf (msg, "%ld %ld %llu %llu", &size, &attr,
        (unsigned long long int *)&tida_c, (unsigned long long int *)&tida_m);

printf ("File size   : %ld bytes\n", size);

printf ("Attributes  : %c%c%c%c%c\n", (attr&FILE_ATTRIBUTE_READONLY )?'R':'W',
                                          (attr&FILE_ATTRIBUTE_HIDDEN   )?'H':'-',
                                          (attr&FILE_ATTRIBUTE_SYSTEM     )?'S':'-',
                                          (attr&FILE_ATTRIBUTE_DIRECTORY)'D':'-',
                                          (attr&FILE_ATTRIBUTE_ARCHIVE   )?'A':'-');

printf ("Create time : %02d.%02d.%04d %02d:%02d:%02d\n", tida_c.day,
        tida_c.mon, tida_c.year + 1900, tida_c.hour, tida_c.min, tida_c.sec);

printf ("Modify time : %02d.%02d.%04d %02d:%02d:%02d\n", tida_m.day,
        tida_m.mon, tida_m.year + 1900, tida_m.hour, tida_m.min, tida_m.sec);

...
```

4.2.9 Command GETINFO:

Query:

GETINFO:\n

Answer:

*GETINFO:VERSION,Ver 4.0 Jan 20 2016 10:01:55
GETINFO:VERSION_EPSNET,Ver 2.6 Jan 20 2016 06:52:43
GETINFO:VERSION_INI,Ver 3.2 Sep 27 2012 08:04:29
GETINFO:VERSION_PLC,CP1004K M 2.7 7.7\n
GETINFO:IPADDR_PLC,192.168.134.176\n
GETINFO:EPSADDR,I\n
GETINFO:EPSPORT,61682\n
GETINFO:PUBFILE,5/5 [FIXED_Foxtrot.pub,//www/webmaker.pub]\n
GETINFO:NETWORK,1/10 [127.0.0.1]\n
GETINFO:\n*

Query:

GETINFO:version_plc\n

Answer:

GETINFO:VERSION_PLC,CP1004K M 2.7 7.7\n

5 Error messages

Server sends two types of messages. The error ones that begin with "ERROR:" and warning ones that begin with "WARNING:". Messages are subdivided into groups each of ten messages.

5.1 List of messages

Error code	Text of message	Group	Type
10	Unable to connect to PLC.	Network communication	Error
11	Maximum connections reached.	Network communication	Error
20	Unable to get data from PLC.	Communication with PLC	Error
21	Unable to send data to PLC.	Communication with PLC	Error
30	Bad client request:	Client queries	Error
31	Incomplete client request.	Client queries	Error
32	Unknown command name:	Client queries	Error
33	Unknown register name:	Client queries	Error
34	Disabled register name:	Client queries	Error
35	Wrong parameter value:	Client queries	Error
40	Unable to get information about file:	File operations	Error
41	Unable to get file:	File operations	Error
50	Unknown name:	Command "SETCONF:"	Error
60	Unknown name:	Command "GETINFO:"	Error
70	Unable to connect to SHARED module.	Shared module	Error
80	Unable to get data from address:	Command "GETMEM:"	Error
81	Unable to set data in to address:	Command "GETMEM:"	Error
250	Changed public file:	Command "SETCONF:"	Warning
251	Public file not changed:	Command "SETCONF:"	Warning
1024	Unknown error.	Not specified	Error

Examples of error messages:

Query:

GET:test\n

Answer:

ERROR:33 Unknown register name: 'test\n

Query:

GET:%R70000\n

Answer:

ERROR:80 Unable to get data from address: '%R70000\n

Query:

EN:test_1 a\n

Answer:

ERROR:35 Wrong parameter value: 'a\n

Query:

SETCONF: pubfile, Test.pub\n

Answer:

WARNING:250 Changed public file: 'Test.pub\n

Or, if the files is not differ:

WARNING:251 Public file not changed: 'Test.pub\n

6 Examples of application

Application of the communication server *PLCCOmS* can be demonstrated on a few simple example programs.

6.1 Example of the simulated PLC in an environment *Mosaic*

Consider a simple program written in the language of structured text “ST”, which will read information about the system time and date, for example, and will calculate the value of a continuous function *sine* and *cosine* depending on run-time. In addition, we have a variable *positive* signaling the positive half-waves of the function *sinus* and one variable of type *STRING* containing the text string.

As testing PLC we choose *FOXTROT CP-1016*.

Example in “ST” language:

```
VAR_GLOBAL // Global public variables
  dat      {PUBLIC} : DATE;
  tim      {PUBLIC} : TIME;
  sinus    {PUBLIC} : LREAL;
  cosinus  {PUBLIC} : LREAL;
  c        {PUBLIC} : LREAL;
  positive {PUBLIC} : BOOL;
  text     {PUBLIC} : STRING;
END_VAR

VAR_GLOBAL CONSTANT
  PI : LREAL := 3.14159265358979323846;
END_VAR

PROGRAM prgMain
  VAR
  END_VAR
  VAR_TEMP
  END_VAR

  dat := GetDate(); // Returns the actual date
  tim := GetTime(); // Returns actual time

  c := c + 0.001; // The time course for the calculation of sine and
                // cosine

  sinus := SIN(c); // Returns sine value of argument
  cosinus := COS(c); // Returns cosine value of argument

  IF sinus > 0.0 THEN
    positive := TRUE;
  ELSE
    positive := FALSE;
  END_IF;

  text := 'Have a nice day';

END_PROGRAM
```

Server allows you to monitor only those system variables that are defined as (PUBLIC). So as variables that can be accessed from outside the program. Public variables can be defined by directive “{PUBLIC}” directly or by dialogue window “*Variable definition*”, where it is necessary to tick the option of the same name (6.1.1).

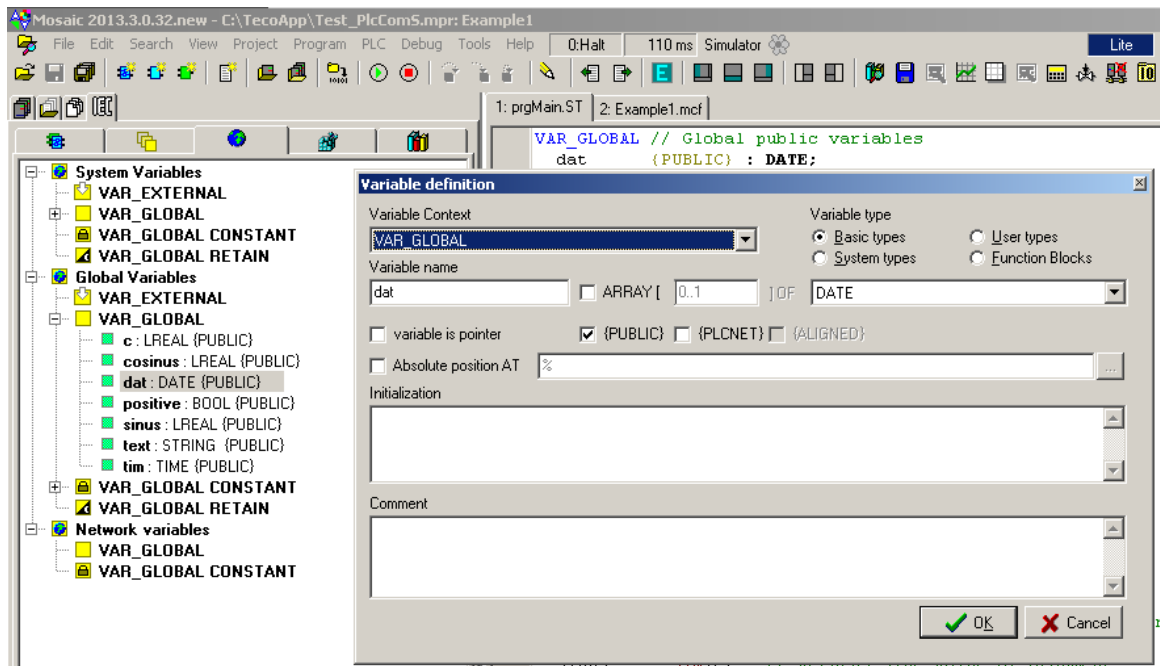


Fig. 6.1.1: The dialog box “Define variables”

If you already have defined all public variables that you want to monitor, you must generate a *public* file (*.pub), a file containing information about the declared public variables. This file may not be automatically generated by the *Mosaic* package. In such case it is necessary to set the generation of that file in “*Project manager*” in the setting menu branch “*Sw – Export files*”, where it is necessary to check the option “*IEC 1131*” (file .exp) and option “*Assembler*” (file .pub) (6.1.2).

The *public* file generated after the user program compilation is stored in the project directory under the name “*project_name.pub*”. The name of this file is used then as the configuration parameter of *ini* file for application of the server *PLCCOmS*.

In case that the file name does not include the relative path in the project directory, it is necessary to copy the *public* file in the same directory from where the server is started!

The finished testing program has to be stored. In “*Project manager*” it is necessary to choose “*Type of connection*” (if the PLC is connected, it has to be disconnected by the “*Disconnect*” button) “*Simulated PLC*” with the checked option “*Mosaic PLC*” and to connect PLC by button “*Connect*” (6.1.3). We compile the program and run it in simulation mode.

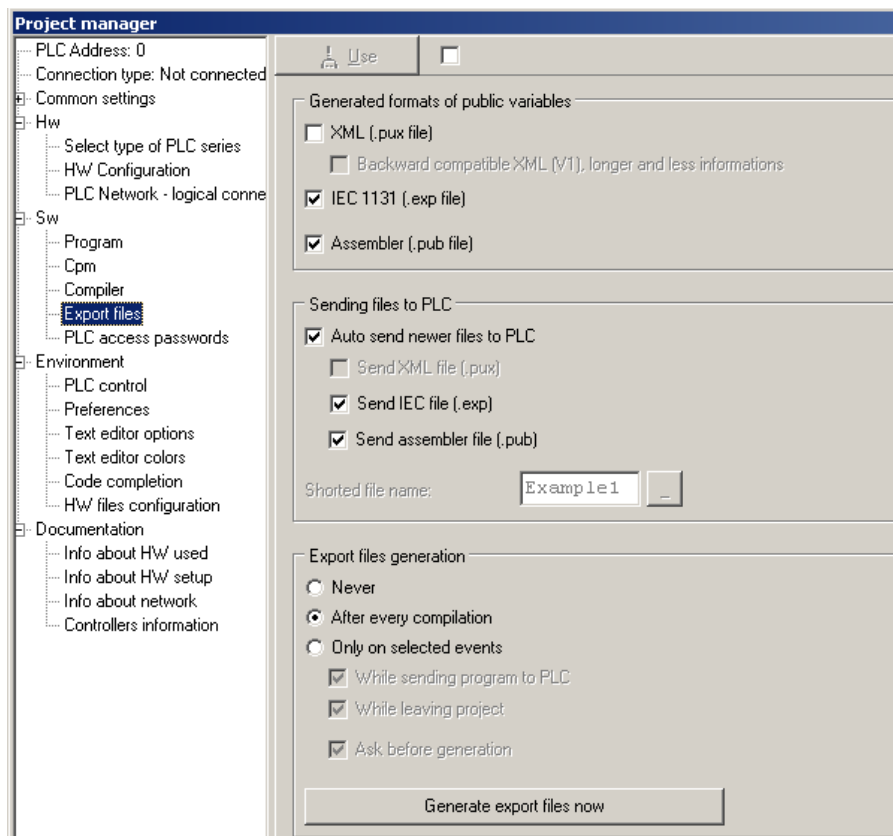


Fig. 6.1.2: Setting of generating export files

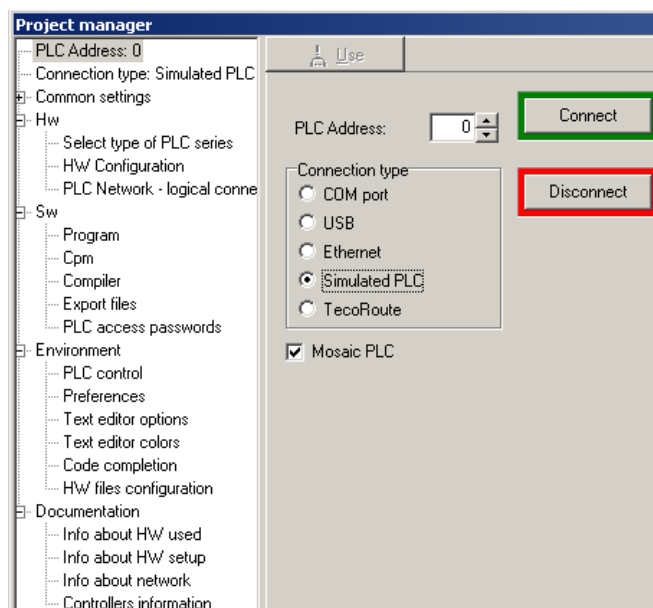


Fig. 6.1.3: Connection of the simulated PLC

Run server with parameters `-c` and `-l`. It will therefore be necessary to specify the name of the configuration (*.ini) and log (*.log) file. In the case of existence of log file the messages of the server are attached to the end of file. The configuration file must be defined. For our example, when observed PLC is simulated by *Mosaic* on the local station (*localhost* – *127.0.0.1*) the contents of the configuration file looks like this:

The contents of the configuration file:

```
# Configuration file for communication server

[*]

NET_CONNECT_MAX = 10          # Maximal amount of clients (Max 32)
FFILE_BLKSIZE   = 1024        # Maximal size of block for files (Max 65536)
FFILE_TIMEOUT    = 300        # Time in seconds for the keeping file
                                in memory (Max 3600)
FFILE_MAXRECS    = 256        # number of files stored in the memory (Max 1024)
END_LINE_CRLF    = Yes        # End of line character (Yes = DOS [\r\n], No =
UNIX [\n])
PF_VAR_DISABLED  = Yes        # Default status for variables

[FOXTROT]          # Alias of used PLC

IPADDR           = 127.0.0.1   # IP address PLC
SERVER_PORT      = 5010        # Port of server
PUBFILE_CRC      = No          # not to verify the checksum for PUBFILE

PUBFILE_FIXED    = <fixedpubfile_name.pub>  # Fixed PUBFILE
PUBFILE          = <pubfile_name.pub>        # PUBFILE
```

If we have the configuration file prepared, we can run the server from the command prompt:

```
..>PLCCOmS.exe -c <config_name> -l <log_name>
```

The success of server startup can be watched in the log file or in case of missing *-l* parameter in the terminal window.

With the running server *PLCCOmS* can someone communicate by the program *Telnet*. For this purpose can be used widespread application *Putty*, through which one can be conveniently connected to the server (6.1.4).

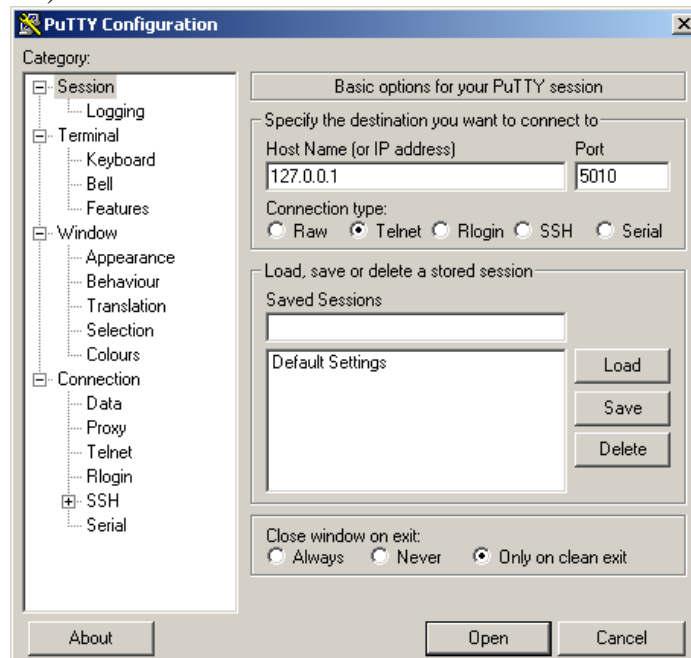


Fig. 6.1.4: Connecting to the *PLCCOmS* server using *Putty*

In the program *Putty* only IP address of the connecting server (if the server *PLCCOmS* runs on the local station, the address is *127.0.0.1*) and the port number on which the server is listening (in our case it is port *5010*). Pressing the button “*Open*” will open the connection.

It is now possible to monitor all public variables that we have in our virtual PLC defined. For these purposes it is necessary to use commands defined by application *PLCCOmS* (e.g. command “*LIST:*” returns a list of all the variables in the PLC).

Server activity can be terminated by the escape sequence “*ctrl+c*”. All the important events of server activity are recorded in the log file.

6.2 Example with the real PLC

We will use the same program as in the previous case. Only instead of a simulated run now we use a real machine, e.g. *FOXTROT CP-1004*.

The set-up steps in the *Mosaic* (generating export files *PUBFILE*) and in the program itself (*PUBLIC* variables) are identical to the first example. The only steps the procedures differ is the type of connection in “*Project manager*”, where the option “*Simulated PLC*” is not used, but the real PLC on the local ETHERNET network is used defined by its IP address (6.2.1). Connect the PLC by the button “*Connect*”, compile the program and turn the PLC into “*RUN*” mode.

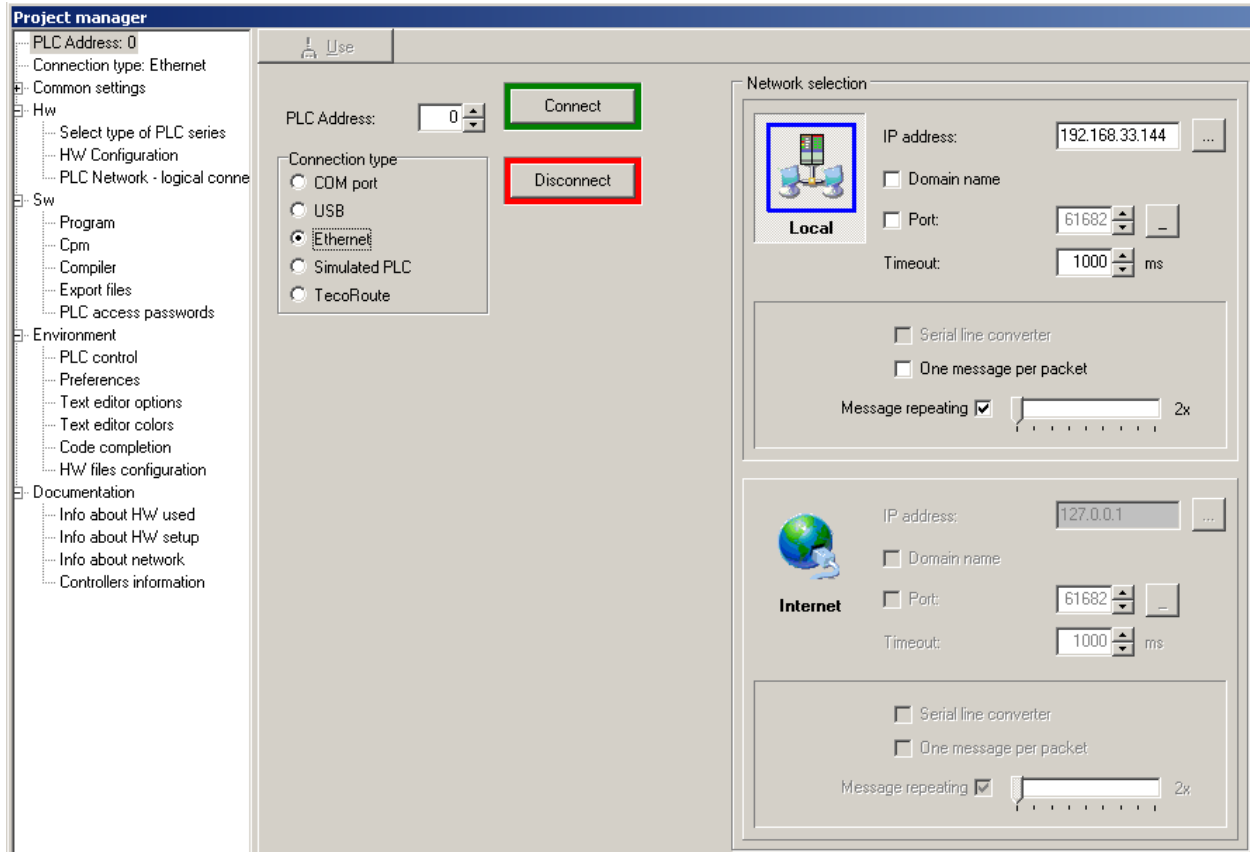


Fig. 6.2.1: Connecting the remote PLC

The configuration file of the *PLCCOmS* application undergo only minor changes comparing to the first example. The only item that is necessary to amend is *IPADDR* (IP address of the PLC), which we change from the local address *127.0.0.1* (for simulated mode) on IP address of PLC local network (e.g. *192.168.33.144*).

Now you can start the *PLCCOmS* server with the specified parameters of configuration file and log file using the command from the prompt (*Example 6.1*).

For the communication with the server is again recommended to use the program *Putty* which supports TELNET with the appropriate settings from the previous example (6.1.4). Warning: do not confuse the IP address of the host station, that is running the server *PLCCOmS*, with address of PLC.

Through the *Putty* program we connect the server, e.g. the IP *127.0.0.1*, if the server is running on the local station.

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8 Supported Operating Systems

OS	Architecture	Compiler
Windows	x86	i586-mingw32msvc-g++
Linux	x86	i586-linux-gnu-g++
Linux	x86_64	x86_64-linux-gnu-g++
Linux	Armel	arm-linux-gnu-g++, arm-none-linux-gnueabi-g++
Linux	Armhf	arm-linux-gnueabi-g++